

Last Time: Overview of our progress...

Fun Fact: If θ is any angle, then

$M = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$ is the transformation matrix of the map

$R_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which rotates every vector of \mathbb{R}^2 by θ radians counter-clockwise (i.e. $M = \text{Rep}_{\mathcal{E}_1, \mathcal{E}_2}(R_\theta)$).

NB: Can be proved pretty easily...

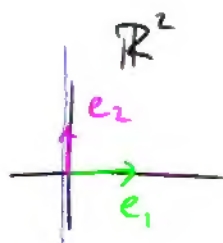
just check for all $0 \neq v \in \mathbb{R}^2$ that Mv is at angle θ with v ...

Let $\theta = \frac{\pi}{2}$. Then $\cos(\theta) = 0$, $\sin(\theta) = 1$ so

$$\text{Rep}_{\mathcal{E}_1, \mathcal{E}_2}(R_{\frac{\pi}{2}}) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}.$$

Recall: If λ is an eigenvalue of operator $L: \mathbb{C}^n \rightarrow \mathbb{C}^n$ with algebraic mult α and geometric mult γ , then $1 \leq \gamma \leq \alpha$.

For $R_{\frac{\pi}{2}}$:



$R_{\pi/2}$



every e-value has
at least 1 e-vector
non-zero

If $0 \neq v$ is an eigenvector of $R_{\frac{\pi}{2}}$, then

$$R_{\frac{\pi}{2}}(v) = \lambda v \text{ for some } \lambda.$$

Q: Where is such a (nonzero) v in our picture?

A: There is none... $R_{\frac{\pi}{2}}$ has complex eigenvalues...

$$P_M(\lambda) = \det(M - \lambda I) \\ = \det \begin{bmatrix} 0-\lambda & -1 \\ 1 & 0-\lambda \end{bmatrix} = \det \begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix} = \lambda^2 + 1$$

So roots of $P_M(\lambda)$ (hence the eigenvalues of M)

$\lambda = \pm i$. Point: Eigenvectors of $R_{\frac{\pi}{2}}$

live in \mathbb{C}^2 , not \mathbb{R}^2 ... Indeed:

$$\underline{\lambda = i}: M - iI = \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \xrightarrow{R_1} \begin{bmatrix} 1 & -i \\ 1 & -i \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -i \\ 0 & 0 \end{bmatrix}$$

$-i \cdot i = -(i^2) = -(-1) = 1$

\therefore System has homogeneous solutions $x - iy = 0$

$$\text{i.e. } \begin{bmatrix} x \\ y \end{bmatrix} \in V_i \text{ iff } \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} iy \\ y \end{bmatrix} = y \begin{bmatrix} i \\ 1 \end{bmatrix}.$$

$\therefore V_i = \text{span} \left\{ \begin{bmatrix} i \\ 1 \end{bmatrix} \right\}$, and

- ① alg mult of $\lambda = i$ is 1
- ② geom mult of $\lambda = i$ is 1.

$\lambda = -i$: Do as an exercise...



Point: we really ought to think of our linear operators as operators on \mathbb{C}^n !!!

Diagonalizability

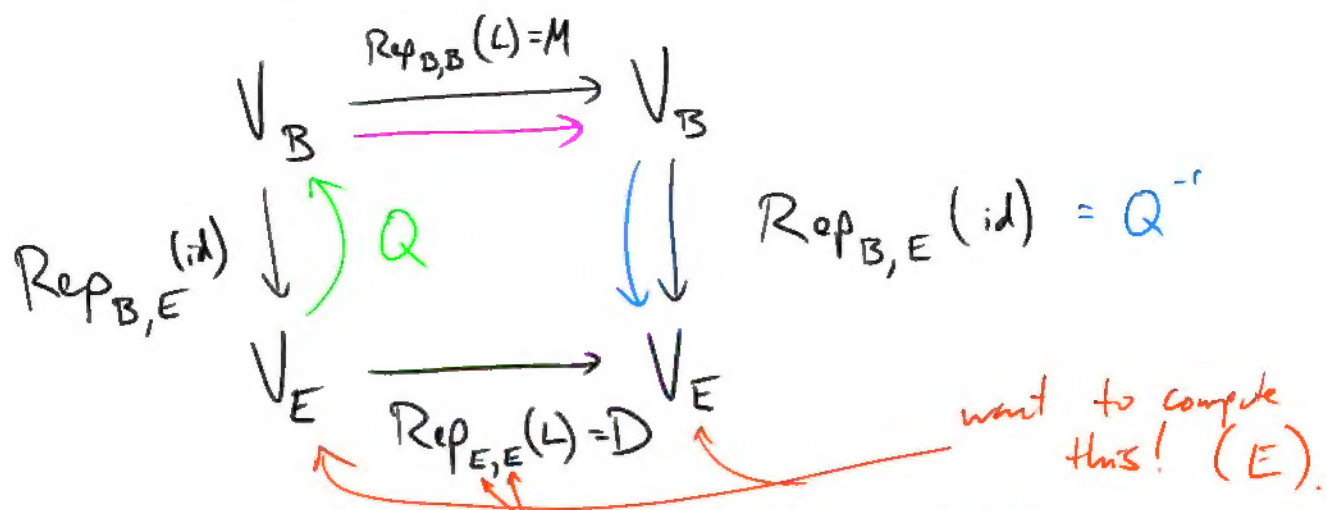
square

Defn: A V matrix M is diagonalizable when

M is similar to a diagonal matrix.

(i.e. $M = P^{-1}DP$ for some P invertible and D diagonal).

Q: If M is diagonalizable, how do we diagonalize?



$$D = \text{Rep}_{E,E}(L) = \text{Rep}_{B,E}(\text{id}) \text{Rep}_{B,B}(L) \text{Rep}_{E,B}(\text{id})$$

$$= Q^{-1} M Q$$

In particular, $Q D Q^{-1} = (Q Q^{-1}) M (Q^{-1} Q)$

$$= (I) M (I) = M$$

So for $P^{-1} = Q$ (i.e. $P = Q^{-1}$) we see $M = P^{-1} D P$.

New Goal: Find a suitable basis E to replace B ...

The diagonal matrix $D = \text{Rep}_{E,E}(L)$ acts on elements of E as eigenvectors! If $E = \{v_1, v_2, \dots, v_n\}$

then $\text{Rep}_E(v_i) = e_i$ ↑ standard basis vector...

So $\text{Rep}_E(L(v_i)) = \text{Rep}_{E,E}(L) \cdot \text{Rep}_E(v_i) = D e_i = d_{i,i} e_i$

where $D = [d_{i,j}]_{i,j=1}^{n,n} = \begin{bmatrix} d_{1,1} & 0 & 0 & \dots & 0 \\ 0 & d_{2,2} & 0 & \dots & 0 \\ 0 & 0 & d_{3,3} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & d_{n,n} \end{bmatrix}$

Point: $L(v_i) = d_{i,i} v_i$ so:

① v_i is an eigenvector of L . ② $d_{i,i}$ is the eigenvalue associated with v_i

③ E is actually a basis of V consisting entirely of eigenvectors of L

Algorithm for Diagonalization: Let $M \in M_{n \times n}(\mathbb{C})$.

- ① Compute $p_M(\lambda) = \det(M - \lambda I)$ characteristic polynomial of M
- ② Compute the roots of $p_M(\lambda)$ (i.e. solve $p_M(\lambda) = 0$ to obtain the eigenvalues of M).
- ③ Compute the eigenspaces V_λ associated to each eigenvalue λ .
(i.e. compute a basis B_λ of eigenvectors for each V_λ).
- ④ If $E = \bigcup_{\lambda \text{ an e-value}} B_\lambda$ is a basis of \mathbb{C}^n , then we have
geom mult = alg mult for all λ ...
computed the desired E . Otherwise, M is not diagonalizable!!!

Remarks: ① In steps 3-4, we used the fact that if $I \subseteq V_\lambda$ and $J \subseteq V_\mu$ are indep and $\lambda \neq \mu$, then $I \cup J$ is also indep in V .

Reason: $V_\lambda \cap V_\mu = \{0\}$ ← very easy ☺.

- ② As part of our construction of E , we noted the entries on the diagonal of D are the eigenvalues of M ☺

Ex: Let $M = \begin{bmatrix} 3 & 2 \\ 0 & 1 \end{bmatrix}$. We diagonalize M as follows:

Characteristic Poly:

$$p_M(\lambda) = \det(M - \lambda I) = \det \begin{bmatrix} 3-\lambda & 2 \\ 0 & 1-\lambda \end{bmatrix} = (3-\lambda)(1-\lambda)$$

Eigenvalues: $p_M(\lambda) = 0 \Leftrightarrow (3-\lambda)(1-\lambda) = 0 \Leftrightarrow 3-\lambda = 0 \text{ OR } 1-\lambda = 0$
 $\Leftrightarrow \lambda = 3 \text{ OR } \lambda = 1$

Eigenspaces:

$$\lambda=1: M-I = \begin{bmatrix} 2 & 2 \\ 0 & 0 \end{bmatrix} \rightsquigarrow \text{RREF} = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

$$\begin{aligned} \therefore V_1 = \text{null}(M-I) &\ni \begin{bmatrix} x \\ y \end{bmatrix} \Leftrightarrow x+y=0 \\ &\Leftrightarrow x=-y \\ &\Leftrightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ y \end{bmatrix} = y \begin{bmatrix} -1 \\ 1 \end{bmatrix} \end{aligned}$$

$\therefore B_1 = \left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\}$ is a basis of V_1

$$\lambda=3: M-3I = \begin{bmatrix} 0 & 2 \\ 0 & -2 \end{bmatrix} \rightsquigarrow \text{RREF} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$\begin{aligned} \therefore \begin{bmatrix} x \\ y \end{bmatrix} \in V_3 = \text{null}(M-3I) &\Leftrightarrow y=0 \\ &\Leftrightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ 0 \end{bmatrix} = x \begin{bmatrix} 1 \\ 0 \end{bmatrix}. \end{aligned}$$

$\therefore B_3 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$ is a basis of V_3 .

Basis Change: Let $E = B_1 \cup B_3 = \left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$. E is a basis of \mathbb{C}^2 because \mathbb{C}^2 has dimension 2 and $\#E=2$

$$\text{Rep}_{E,E_2}(\text{id}) = \text{Rep}_{E_2,E}(\text{id})^{-1} = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix}^{-1} \text{ is computed via:}$$

$$\left[E \mid E_2 \right] = \left[\begin{array}{cc|cc} -1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{array} \right] \rightsquigarrow \left[\begin{array}{cc|cc} 1 & 0 & 0 & 1 \\ -1 & 1 & 1 & 0 \end{array} \right]$$

$$\rightsquigarrow \left[\begin{array}{cc|cc} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 \end{array} \right] = \left[I \mid \underline{\text{Rep}_{E,E_2}(\text{id})} \right]$$

$$\begin{array}{ccc} V_E & \xrightarrow{D} & V_E \\ \text{Rep}_{E,E_2}(\text{id}) \downarrow & & \uparrow \text{Rep}_{E_2,E}(\text{id}) \\ V_{E_2} & \xrightarrow{M} & V_{E_2} \end{array}$$

$$\begin{aligned} D &= \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix}^{-1} \begin{bmatrix} 3 & 2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 1 \\ 3 & 3 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}. \quad \square \end{aligned}$$